Considerations for virtual surgical planning and simulation in orthognathic surgery—a narrative review

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Abstract: Although there are many benefits to use 3D virtual surgical planning (VSP) for orthognathic surgery, there are only a few reports on the potential errors or mistakes that can occur with VSP and simulation processes. This narrative review updates information on VSP and discusses the various precautions and considerations for VSP in orthognathic surgery. Application of VSP allows visualization of the interosseous relationship, segment overlap or bony interference, and significant interosseous gaps. Potential sites for additional bone grafts or bone reduction can be anticipated. Additionally, presurgical planning can be performed with unlimited time. Since most VSP is performed by an outsourced company, quality assurance in VSP depends on a third-party, and sometimes there is lack of clarity when delineating the responsibilities for surgical outcomes. To increase the precision of 3D planning and simulation, surgeons need to be aware that the VSP cannot automatically ensure the success of surgical outcomes. Errors can occur at every step, such as integration of 3D dentition to skull data, segment identification and mobilization, computer-aided surgical simulation, fabrication of splint and surgical guides, 3D image superimposition, and determination of occlusion in virtual space. Thorough understanding of the source of errors in VSP can lead to successful surgical outcomes in orthognathic surgery performed with VSP.

Keywords: virtual surgical planning (VSP); simulation; orthognathic surgery; three-dimensional (3D)

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Introduction

In patients with facial deformities, such as malocclusion, surgical planning and simulation of surgical outcomes are the most important processes in presurgical workups for successful orthognathic treatment. It is necessary to correctly move the osteotomized segment and dentition to the required position in 3D space according to the preoperatively determined surgical plan. Therefore, intraoperative control of precise and accurate mobilization of osseous segments is emphasized. Currently, computer-assisted virtual surgical planning (VSP) has been widely introduced in various institutions and it is commonly used in oral and maxillofacial surgery, especially in the field of orthognathic surgery (1-4). Three-dimensional (3D) VSP is widely accepted as mainstream for treatment planning compared to the previous classical 2D planning or articulator model surgery (4,5). The accuracy and feasibility of VSP for orthognathic surgery is well documented in the literature (6-9). Using computerized treatment planning, it is possible to perform virtual segmentation of the maxilla or mandible and repositioning of the osteotomized segment is therefore possible. This enables precise mobilization of the horizontal, vertical, and transverse direction segments with six degrees of freedom according to the planned movements. At the same time, it is possible to visualize
the interosseous relationship, segment overlap or bony interference, and significant interosseous gaps and potential sites for additional bone grafts or bone reduction. Another advantage is that the trial of presurgical planning can be performed within an unlimited time.

Technological advancements enable not only virtual planning but also intraoperative utilization of surgical splints or surgical guides fabricated by a 3D computer-aided design/computer-aided manufacturing (CAD/CAM) system. A step-by-step protocol for 3D VSP is well established at each institute even though there are some minor technological differences. Overall, the protocol is composed of several steps: (I) acquisition of computer tomography (CT) or cone-beam computed tomography (CBCT) images of maxillofacial structures and scanned maxillomandibular dental casts; (II) 3D image segmentation, fusion, and 3D superimposition of dental arches in CT images for virtual planning; (III) implementation of virtual treatment planning based on the diagnosis and surgeon’s plan for the surgery; (IV) fabrication of CAD/CAM-utilized surgical splints or surgical guides; (V) intraoperative utilization of surgical splints or surgical guides—surgical transfer of planned surgical movements; and (VI) postoperative validation of the VSP compared to real postoperative results (1,10,11). Recently, surgical guides accompanied by pre-bent titanium plates (12) or patient-specific, 3D printed plates are being used with (13) or without an intermediate splint (14).

Since the osteotomized segments of the maxilla can be mobilized to complex degrees and directions, 3D planning and simulation are very helpful for accurate 3D simulation. Previous reports have shown that the application of VSP demonstrated acceptable surgical accuracy in one-piece maxillary osteotomy (15-18) or multipiece maxillary orthognathic surgeries (19-24). Many previous publications have emphasized and highlighted the accuracy of a 3D planning system using the various software programs and hardware. However, the enthusiasm for 3D technology sometimes underestimates or ignores the potential source of errors during virtual planning. Moreover, a systematic review of virtual planning in orthognathic surgery suggested that even though there has been no reported financial conflict of interest, there is a risk of financial bias in some studies because of the possibility of financial gains from 3D software development and application (7).

In this narrative review, the studies suggesting quantitative data is included to reduce the bias of the publication. Since the VSP is recently shown in oral and maxillofacial areas, publications showing important concepts or explaining operating process of VSP were also reviewed.

Although there are many benefits to using 3D VSP for orthognathic surgery, there are only a few reports on potential errors or mistakes that can be encountered with VSP and simulation processes. The key questions in this review was as follows: (I) which process during VSP can be the source of errors? (II) what is different between in-house and outsourced VSP? To answer these two key questions, this review aims to update information on VSP and discuss the various precautions and considerations in VSP for orthognathic surgery.

We present the following article in accordance with the Narrative Review Checklist (Available at http://dx.doi.org/10.21037/fomm-20-54).

Methods

In these reviews, PubMed data base search was performed following terms: Orthognathic Surgery, Computer-assisted, computer-aided, virtual planning, CAD-CAM. The published reports from Jan 2000 to April 2020 in English were included. Study with full-text were selected and reviewed.

Discussion

Practical advantage of computerized surgical planning in orthognathic surgery

VSP can facilitate the quantitative analysis of outcomes and provide greater accuracy in orthognathic surgery (6). Therefore, computerized planning and simulation for orthognathic surgery would allow surgeons to perform more accurate and efficient orthognathic surgeries (8,25). There are various advantages to VSP-modulated orthognathic surgery.

First, more accurate and quantitative analysis of the various deformities is possible with VSP, which previously were impossible with 2D cephalometric analysis. Computerized planning in orthognathic surgery allows surgeons to carry out comprehensive evaluation of anatomical structures of the surgical field. In asymmetric patients, VSP can be used to diagnose presurgical problems and can predict the postoperative 3D position of osteotomized segments, thereby predicting redundant asymmetry after surgery (26). At the same time, the need for dental decompensation after surgery can also be visualized
and it is possible to reflect the magnitude of overcorrection to VSP in advance (1).

Another advantage is that VSP can allow minimally invasive surgery. VSP follows the osteotomy line nearly the same as in a real intraoperative osteotomy. Repetitive virtual surgery for the best possible results in problematic cases can minimize the surgical errors and can allow the surgeon to accurately reproduce the surgical plan. At the same time, surgeons can anticipate potential intraoperative problems and reduce complications using VSP.

Additionally, residents can participate in the planning procedure and can have deeper insights on the surgery being planned. Patients can have sufficient information on the surgery and can understand postoperative sequelae more easily. It is very useful for patient and student education.

Validation of the surgical outcome can be carried out with postoperative assessment. Since all the data related to computerized surgical planning and postoperative outcomes are stored in a database, these accumulated quantitative follow-up data would be helpful for developing an improved protocol or technical innovations for further treatments.

Potential source of errors in computer-assisted planning and surgical applications

Since the actual surgical result is significantly influenced by the simulated maxillary position in virtual surgery or articulator model surgery, the intermediate splint or surgical guide is important and this core step can determine the accuracy of the surgery (Figure 1). The many steps of a conventional articulator-based model surgery allow a high probability of errors. The step of taking an impression, bite registration, facebow transfer, maxillary repositioning and splint fabrication on an articulator can be sources of errors (Figure 2). However, a VSP does not directly guarantee surgical accuracy. Inaccuracy associated with a computerized planning procedure exists for many factors; e.g., head positioning, 3D data integration, segment positioning, and the stereolithographic splint fabrication procedure.

Errors in 3D data integration and fusion

It is important to integrate the 3D data of dentition and the skeleton from different imaging techniques to create a 3D virtual dentofacial skeleton in the same virtual space. Because
orthodontic brackets, metallic restorations, and a prosthesis are usually installed in many patients, metallic artifacts in CBCT images are a significant problem (27). Therefore, dentition is usually determined with laser surface scanning and it requires image fusion from skeletal CT scans. Many technical developments have been reported to overcome radiographic artifacts that can interfere with the optimal integration of maxillomandibular dentition using CT images. Multiple scans (28,29), fiducial markers (19,30-32), registration blocks (19,33), surface matching (34-37), voxel based registration (29), or a specialized algorithm using a combination of various methods (38) are suggested to improve the accuracy of 3D data integration of dentition and the skeleton. Currently, the function of point or surface registration in 3D planning software is used often (39). The dental arch information STL file format is usually introduced in 3D simulation software.

The registration process is performed by: (I) matching corresponding reference points that are close to each other, (II) using regional surface-based registration (3D & MPR images), and 3) validating the superimposition accuracy (Figure 3). However, other factors remain a concern; e.g., (I) the time interval between obtaining the dental impression or intraoral scan vs. CBCT imaging because of potential effects of presurgical orthodontic movements; and (II) the intermaxillary occlusal relationship between the dental cast vs. CBCT (centric relation or centric occlusion bite).

Complete, perfect integration of an individual maxillary or mandibular dental cast to CBCT is not always possible but it has clinically acceptable accuracy with current technology.

**Errors in the virtual planning process—head positioning, segment positioning**

The head position in virtual space is important for treatment planning. The vertical position reference landmarks or occlusal plane are especially important for maxillary mobilization (Figure 4). Moreover, the 3D reference plane in virtual surgical movements should coincide with the real pre-postoperative head position. Otherwise, validation of the 3D VSP is not possible. The 3D reference plane is frequently defined by anatomical landmarks, such as Frankfort’s horizontal plan (40). The natural head position can also be used in VSP but has some limitations because of reproducibility (41) or changes after mandibular set-back (42) or advancement surgery (43).

After orienting the head position in 3D virtual space, segmentation of the individual osseous segments is carried out by cropping the target structure and cleaning up the artifacts or unnecessary 3D structures and virtual osteotomy (11). During the VSP, the midline deviation, maxillary roll, pitch, yaw correction, and anteroposterior/vertical transverse correction need to be thoroughly confirmed. It is common to use commercially available software; such as, SimPlant O&O® (Materialise), Mimics® (Materialise N.V.,
Figure 3 Step-by-step procedure for image fusion of dental model and 3D cone-beam computed tomography (CBCT) data. Creation of a 3D maxillofacial-dental model using sequential point-matching (A) and regional surface-based registration (B). Comparison of an original 3D CBCT image of the skull model (C), initial incorporation of dental arch information into the 3D CBCT skull structure (D), and finally superimposition of the dental-skeletal data (E).

Figure 4 Setting the head position is important in VSP. It is necessary to confirm the head position of the patient before starting segment mobilization. The reference plane of the planned movement of the segment can be different for each patient.
Leuven, Belgium), Dolphin Imaging® (Dolphin Imaging and Management Solutions, Chatsworth, CA, USA), ProplanCMF® (Materialise), and various other software programs developed by individual institutions or local companies. According Xia et al. (2015), it is recommended to perform VSP following a specific algorithm; i.e., midline correction followed by roll and yaw correction, adjustment of the vertical position, pitch orientation, and horizontal position consecutively (11). Other institutions have suggested using an algorithm that starts with transverse correction of the midline and roll correction at first in a frontal view, then performance of pitch correction in a lateral image, and performance of maxillary yaw correction as the final stage (44). The algorithm can be modified according to the practitioner’s preference and function of the module in the 3D simulation software.

One of the strong advantages of 3D VSP is precise visualization of the anticipating position of the segments (Figure 5). It is easy to identify interosseous interference during the VSP process. Severe interference between the proximal and distal segments of the mandibular ramus after a planned surgery can be controlled by yaw correction of the maxillary osteotomy (44). For example, in a patient with severe facial asymmetry, canting correction can be planned with the center of rotation at the upper incisor midline. As a result, a significant gap on the deviated side would be expected. If the yaw correction of the maxilla is added in this position, the interosseous gap can be reduced (Figure 6). On the contrary to this advantage, unwanted yaw correction can be accompanied by any amount of roll correction and the midline position must be correct during canting correction of the maxilla via VSP. Therefore, after all the planned movement is finished, the position of the osteotomized segment needs to be confirmed again for every x, y, z reference point (Figure 7). VSP can be used to predict and manage the interosseous interference or gap and minimize surgical morbidity and operation times (45).

Severe bony interference can be corrected with the 3D VSP procedure. However, accidental mobilization in virtual space can lead to surgical error. VSP can overcome the potential difficulties in articulator model surgery (17,46) or inaccuracy of the articulator-based conventional model surgery (47). For example, when a maxillary down fracture or asymmetric maxillary impaction with down fracture on the contralateral side are needed, they are definitely accompanied by premature contact with bilateral or unilateral molars. Therefore, intermediate splint fabrication using minimal changes in the temporomandibular joint position would be difficult with articulator-based model surgery. However, mandibular autorotation is possible in virtual space by centering the line connecting the center of the bilateral condyle head (Figure 8).

**Precision in orthognathic surgery with a surgical guide and prefabricated plates**

There are many reports on the accuracy and feasibility of 3D CAD/CAM splints. It is currently an important component of the orthognathic surgery process (6,48-51).
To accurately transfer VSP to the operating room, surgical guides can also be used with or without a surgical splint (52). Surgical guides can aid two functions in surgeries; i.e., osteotomy and repositioning (53). Currently, surgical guides that utilize custom titanium miniplates showed favorable surgical accuracy (54-58). Short operating times have great advantages, but a limitation is the high cost of these systems (54,56). Previously reported results have suggested that CAD/CAM surgical guides and utilization of customized titanium plates are a major trend in orthognathic surgery and can eliminate the need for intermediate surgical pauses to reposition the maxilla.

**Digital workflow of VSP for orthognathic surgery using in-house processing vs. outsourcing**

The 3D software programs for VSP are usually installed at the hospital and the surgical team can design the surgical plan at each institution. Surgical plans can be accessed throughout the individual hospital via computer networks or web-based connections. Residents, patients, and operators have easy access to the 3D plans. This can facilitate in-

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**Figure 6** One example of performing a yaw correction. After maxillary canting correction with the center of rotation the upper incisor midline, there would be a significant gap on the deviated side (A). If the yaw correction of the maxilla is added, the interosseous gap can be reduced (B).
In maxillary canting correction, right side impaction and left side down fracture is nearly the same and there is no difference in the maxillary incisor midline (A,B). However, posterior yaw correction can be accompanied erroneously (B).

A depth discussion on a surgical case and activate multiple opinions on difficult cases, thereby minimizing potential mistakes. A hospital or institution that houses a laboratory that is specialized for 3D planning and CAD/CAM splint or guide fabrication is optimal for surgeons. However, considering the various obstacles in hiring experts and the flexibility in the number of the operations and management costs for 3D laboratories, outsourcing of VSP is adopted in many institutions.

CAD/CAM-assisted surgical planning in orthognathic surgery is frequently carried out by outsourcing in conjunction with a third-party vendor. Many private companies offer outsourced VSP, such as 3D Systems (VSP® Orthognathics) (59), Materialise (ProPlan CMF) (60), KLS Martin (IPS CaseDesigner®) (13) or other domestic companies in each country or local district. In the process of establishing a surgical plan, surgeons confer with 3D technicians from the above mentioned companies. During an example VSP on-line meeting, a patient’s intermaxillary occlusion was virtually aligned and the surgeon confirmed the finally expected occlusion after the surgery. The osteotomized segments were repositioned according to
the occlusion and surgical plan. Therefore, a web-based meeting or interactive discussion is important to minimize the knowledge gap between the surgeon and technician.

The use of outsourced VSP systems is advantageous in many clinics. However, there are limitations in outsourcing, such as the high cost of processing, prolonged delivery time before surgery, and necessity for multiple web-meetings or conference calls for manufacturing outsourced CAD/CAM-splints or surgical guides. Therefore, the need for processing VSP using in-house workflow has been suggested (61-63). 3D printed models can be fabricated from commercially available 3D printers at the clinician’s institution and can reduce the preparation phase and minimize delivery time and can be used to train residents to understand 3D processing and simulation. It is still a demanding situation for a surgical department to hire professionals who can work faster with reasonable costs compared to an outsourced company.

There are limitations and quality of research reviewed. There can be inherent publication bias. Because of recent strong enthusiasm for application of VSP in orthognathic surgery, most of the problems are not seriously screened. Moreover, the scientific evidence are relatively low in previous literatures and there is not so many well-designed randomized control data. Studies using more objective inclusion/exclusion criteria with large number of data need to be investigated further in future research.

Figure 8 Virtual mandibular rotation to minimize inter-segment interference. When the maxillary downward reposition is planned (A), autorotation of mandible hinged on TMJ center is needed to fabricate an intermediate splint (B).

Summary

VSP plays an important role in orthognathic surgery in the era of digital technology. It has been suggested that VSP would be an opportunity rather than a risk factor for surgery because there is significant evidence of decreased preparation times, operation times, increased accuracy, and enhanced satisfaction of practitioners. Updates in the latest advances in computerized planning is important for surgeons who treat patients with dentofacial deformities. Understanding the benefit vs. limitations and cost and time efficiency vs. inefficiency can enhance the understanding of trends in VSP and can determine the best possible clinical settings in individual institutions.

Currently, many institutions perform VSP using outsourced companies. This has inherent risk of exposure of patient information and intellectual resources. This information also has a significant relationship with the development of better VSP. Moreover, all the quality assurance in VSP steps depend on the third-party and there is a gray zone to determine the exact responsibility for the surgical outcomes. To overcome the problems of outsourced VSP, in-house planning is considered to minimize communication gaps and reduce the cost and time for VSP planning. However, the decision can be made depending on the medical environment of individual institutions.

Since there are many factors determining the precision
of 3D planning and simulation, the surgeons need to be aware that the VSP cannot automatically ensure successful surgical outcomes. Errors can be encountered at every step. Integration of 3D dentition to skull data, segment identification and mobilization, computer-aided surgical simulation and fabrication of splint and surgical guides, 3D image superimposition, and determination of occlusion in virtual space are factors that need consideration. Thorough understanding of the source of errors in VSP can lead to successful surgical outcomes in orthognathic surgery performed with VSP regardless of in-house or outsourced virtual planning procedures.

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Footnote

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